

Sub  
C  
end

B2  
cancel

(d) [c] defining third or more rank points adapted to the contour of the object by iteratively dividing each new segment [each segment is iteratively divided] into subsegments [adjusted by defining third rank points adapted to the contour of the object], so as to constitute a third or more three-dimensional shape closer to the contour of the object than the second three-dimensional shape, the creation of the [a] third or more rank points [point] resulting in the creation of two additional new facets and three additional new segments; and

(e) [(d) then] calculating the volume of the third or more three-dimensional shape. [is calculated.]

2 (amended). The method according to claim 1 wherein the [films are] volume of the object comprises images taken along parallel sections.

Claim 3, line 1, change "films is" to -- images --;

, line 2, change "treated to supply" to -- provides --;

Claim 7, line after "each" insert -- of the --;

, line 2, after "second" insert -- rank --;

Claim 8, line 2, after "second" insert -- rank --;

Claim 10, line 2, after "second" insert -- rank --;

Claim 11, line 2, after "second" insert -- rank --;

Claim 12, line 2, after "second" insert -- rank --;

Claim 13, line 2, after "second" insert -- rank --;

B4

14 (amended). The method according to claim 1, wherein the segments are divided into further additional subsegments until the change in volume for each further iteration resulting from a given division [is negligible] reaches a volume according to the desire of the operator or as defined by preset conditions.

Claim 16, cancel.

Claim 18, line 1, after "wherein" insert -- any of --;